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Research Article

A SOA-Based Embedded Systems Development Environment for Industrial Automation

K. C. Thramboulidis, G. Doukas, and G. Koumoutsos

Electrical and Computer Engineering, University of Patras, 26500 Patras, Greece

Correspondence should be addressed to K. C. Thramboulidis, thrambo@ece.upatras.gr

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Currently available toolsets for the development of embedded systems adopt traditional architectural styles and do not cover the whole requirements of the development process, with extensibility being the major drawback. In this paper, a service-oriented architectural framework that exploits semantic web is defined. Features required in the development process are defined as web services and published into the public domain, so as to be used on demand by developers to construct their projects' specific integrated development environments (IDEs). The infrastructure required to build a web service-based IDE is presented. Specific web services are defined and the way these services affect the development process is discussed. Special focus is given on the device model and the means that such a modelling can significantly improve the development process. A prototype implementation demonstrates the applicability and usefulness of the proposed demand-led development process in the industrial automation domain

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1. INTRODUCTION

The state-of-the-art in methodologies, techniques, and tools, that support the embedded systems development process is unsatisfactory and many years behind the ones used in the traditional software development process [1]. Even more, currently used development technologies do not take into account the specific needs of embedded systems development [2]. At the same time, even though the need for embedded devices increases and becomes more demanding, their development process is becoming more and more complicated by the increasing tendency to shift functionality and complexity from hardware to software.

Software engineering practices such as component-based and model-driven development are already exploited to develop distributed embedded systems. Descriptions of ready-to-use software and hardware components that are required for the model-driven development of embedded devices are already available on the web. Web browsers and search engines provide the only means to search for the required hardware or software components, as far as this information is constructed in the current traditional way, that is, using presentation languages such as HTML in the best case. It is very

difficult if not impossible for this information to be utilized by integrated development environments (IDEs) to semiautomate the development process.

On the other hand, it is almost impossible for one methodology and one toolset to cover the whole range of embedded systems [1], even though a number of component models [3] evolved during last years to address the specific requirements of their development process. The embedded systems' developer to effectively address the complex development process wants to pay only for the resources actually used to solve the specific problem, and monolithic environments do not cover this requirement.

In this paper, an approach to address the above problems is presented. Semantic web [4] provides a solution to the first problem, while service-oriented computing [5] provides the infrastructure to address the latter. Technologies of the semantic web, such as the Web Ontology Language (OWL) [6], can be exploited to formalize component descriptions and make them machine-interpretable so that they can be more easily analyzed by IDEs to assist the developer in the decision making processes involved in embedded systems development. Using this technology domain models for devices, device components, software components, and so forth can

be constructed, uploaded on the web, and utilized by IDEs to semiautomate the development process. On the other hand, service-oriented computing provides the infrastructure required to build an Embedded Systems' Engineering Support Environment (eSESE), where the requirements of the developer for the development process will have the principal role. The developer, based on these requirements, should be able to set up and customize a project-specific eSESE by easily integrating through plug-and-play the desirable features that should be provided through a service-oriented architecture-(SOA-) [7] based framework.

A service-oriented architectural framework for the exploitation of service-oriented computing in the development process of embedded systems is defined. Features required in the development process, such as component type, component network and system layer editing, implementation model generation, and component network verification, that will exploit semantically annotated component descriptions, are defined as web services (WSs). Developers are allowed to implement their own desirable features and incorporate them into the framework. This provides a powerful and flexible framework for customizing and yet extending the environment to address the developer's particular needs. The developer, instead of buying or developing software components and bind them together to form the development toolset, will construct the project-specific eSESE as an orchestration of web services that are only used and bound together at the time of use of the particular feature of the eS-

The device modelling process is used as an example to present the benefits of the proposed approach. The need for a device model in the context of this approach is discussed. An ontology-based framework for such a device model is defined and a prototype implementation to demonstrate the applicability and usefulness of the proposed approach in the industrial automation domain is presented. To our knowledge, there is no other work at the moment towards the direction of utilizing SOA for the definition of an engineering environment in the form of an eSESE that will exploit the advantages of semantic web in service and component specification.

The remainder of this paper is organized as follows. In the next section, a brief introduction to the basics of SOA and semantic web is given, along with a reference to their use in industrial automation. In Section 3, the proposed service-oriented architectural framework is presented. Section 4 focuses on device modelling as an example of modelling a constituent component of embedded systems. The need for a common device model is discussed and a solution to this problem is proposed. The different scenarios of using the device model through the system development process are also presented. A prototype implementation is described in Section 5 and finally the paper is concluded in the last section.

2. BACKGROUND AND RELATED WORK

Software engineering practices such as component-based development can be exploited to develop distributed embedded systems (DESs) for industrial automation. However, main-

stream component models such as DCOM, EJB, and NET are not suitable for the embedded systems' domain. A number of component models evolved during the last years to address the specific requirements of the development process of embedded systems [3]. Some of these are general purpose, such as CORBA-CCM [8], PECOS [9], PECT [10], the embedded object architecture [11], DECOS [12], while others are domain-specific such as the Function Block model defined by the IEC 61499 standard [13], Ptolemy [14] and Giotto [15] for the control and automation domain, the Koala model [16] and the one defined in [1] for consumer electronic software, the Rubus component model [17] for resource constrained real-time systems, the SaveCCM [18] for vehicular systems, and the PBO [19] for the development of sensorbased control systems with specialization on reconfigurable robotics applications.

IDEs supporting the various component models provide the infrastructure required to exploit the specific models in the development process. General purpose as well as domain-specific IDEs are currently available and a number of projects are on the way for the development of such IDEs. For example, the DECOS toolset and the Archimedes ESS [20] have been developed on top of the general modelling environment (GME) [21]. The former provides a model-based environment for the embedded systems domain, while the latter for the control and automation domain.

Today's IDEs are mainly based on a monolithic proprietary toolset and their objective is to assist the developer in constructing component types and system design diagram specifications, validating the design specifications, and deploying and executing complex DESs. However, most of the toolsets cannot fully support an effective development process. Embedded systems' developers for industrial automation need improved techniques, methodologies, and tools to better support the analysis, design, debugging, validation, deployment, and verification of the system and currently available IDEs do not fully cover these requirements [22]. Even more, developers will have to select the toolset that best fits their development requirements and, in most of the cases, the existing or under-development tools do not address all of these needs. At the same time, it is almost impossible for one methodology and one toolset to cover the whole range of DESs, as embedded systems vary considerably in their requirements.

The embedded systems' developer to effectively address the complex development process of the next generation agile DESs in industrial automation wants (a) to pay only for the resources actually used to solve the specific problem, and (b) to be able to extend these toolsets to suit project-specific needs. SOA and semantic web are exploited in this work to create the infrastructure required to address these requirements.

2.1. Service-oriented architectures

Software architectures have emerged as an important discipline for software engineers that were looking for better ways to understand their systems and new ways to build larger, more complex software systems [23]. The software

architecture involves, according to Shaw and Garlan, "the description of elements from which systems are built, interactions among these elements, patterns that guide their composition, and constraints on these patterns."

However, as the level of complexity of today's systems is continually increasing, traditional architectures that have been defined over the last years seem to be reaching their limit in their ability to enable IT organizations to meet today's complex set of challenges [23]. Brereton and Budgen in [24] argue that although component-based development, one of the recent architectural styles, offers many potential benefits, such as greater reuse and a commodity-oriented perspective of software, it also raises several issues that developers need to consider.

Service-oriented computing [5, 25] and SOA are being promoted as the next evolutionary approach to address these problems. SOA, which is not only an architecture but also a programming model, defines a new way of thinking about building software systems. A service-oriented architecture is essentially a collection of services along with an infrastructure that enables these services to communicate with each other [26]. This communication can be simple as the case of simple data passing or as complex as the case of two or more services coordinating to accomplish a higher layer activity.

A service is a function that is well-defined, self-contained, and does not depend on the context or state of other services. A service has many characteristics that an architect must consider and specify as required. Performance, capacity, business organization, risks and issues, ownership, reliability, security, business impact, tolerance, service contract, and dependencies constitute a list of characteristics for which a service requires further specification [27]. However, all services do not require the same level of definition. In any case, the following two questions "what does the service do"? and "what is the major functionality required by the user"? should be clearly answered by the specification of the service. The central role of the specification of user's required functionality is the issue that differentiates SOA from object-orientation [27]. Thus the primary construct of SOA is the service that represents how its consumers wish to use the system, while that of object technology is the object that represents an entity as structure and behavior.

The concept of service-oriented architecture appeared from the time CORBA [28] provided the first infrastructure to integrate applications running on different heterogeneous platforms. Faster time-to-market, reduced cost, risk mitigation, continuous business process improvement, and process-centric architecture are among the most important benefits of applying SOA [24]. However, the most important advantage of SOA for the industrial automation domain is that it can evolve on existing system investments rather than requiring a full-scale system re-engineering. Legacy systems can be encapsulated and accessed via service interfaces, preserving the huge amount of investment in this area.

A service-oriented architecture is essentially a collection of services along with an infrastructure that enables these services to communicate with each other. Web services, which provide the infrastructure required to connect services together into a service-oriented architecture, are a collection of technologies, including XML, SOAP, WSDL, and UDDI, that can be used to implement a service-oriented architecture. They let you build programming solutions for specific messaging and application integration problems. The Web Service Definition Language (WSDL) is expected to become the de facto standard for describing services in the next few years. So, defining existing industrial automation systems using WSDL will allow industry to add agility to their IT environments.

Other research groups are already exploiting SOA, web services, and semantic web in industrial automation [29-33]. The Global Understanding Environment (GUN) [29] is a middleware framework used to achieve interoperation, automation, and integration in building complex industrial automation systems consisting of components of different nature. Semantic web services and agent technologies are exploited in GUN to make heterogeneous industrial resources web-accessible, proactive, and cooperative ready to automatically plan their own behavior, monitor, and correct their own state, communicate, and negotiate depending on their role. The Service-Oriented Device Architecture (SODA) [30] attempts to integrate business systems through a set of services that can be reused and combined to address changing business priorities. According to SODA, a device integration developer would be responsible for encapsulating devices as services. The SIRENA approach [31] intends to create a service-oriented framework for specifying and developing distributed applications in diverse real-time embedded computing environments. The use of semantic web services (sWS) is proposed in [32] to address the challenge of rapid reconfiguration of manufacturing systems required in order to evolve and adapt to mass customization. A dynamic ontological definition of the generic industrial resource to allow flexible management, maintenance, and monitoring of industrial processes is described in [33].

2.2. Semantic web

Semantic Web [3] is expected to become the next generation of the web assuming that besides the existing content, there will be a conceptual layer of machine-understandable metadata, giving well-defined meaning to the information, and making it available for processing by software agents. Next-generation applications will address the interoperability problem between heterogeneous systems by exploiting such metadata to perform resource discovery and integration based on their semantics.

Ontologies and problem solving methods have become key instruments for the development of the semantic web [34]. An Ontology, which is a formal explicit specification of a shared conceptualization, defines "the basic terms and relations comprising the vocabulary of a topic area as well as the rules for combining terms and relations to define extensions to the vocabulary" [35]. An ontology is a key concept for capturing domain-specific consensual knowledge in the form of a common vocabulary that allows its sharing by a group. Classes, relations, formal actions, and instances are the main components of an ontology. Basic concepts are represented by classes, while associations between concepts

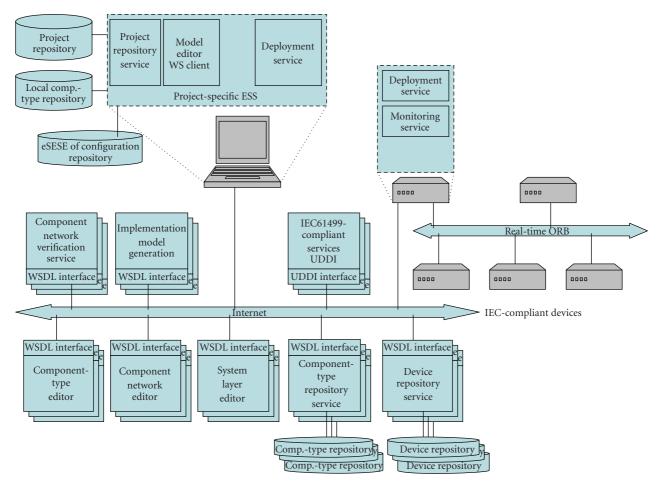


FIGURE 1: An SOA-based framework for the development of embedded systems.

are represented by relations. Binary relations are used to express the attributes of the concept. Elements or individuals are represented as instances and formal axioms are used to model sentences that are always true. Ontologies promise to

- (i) share common understanding of the structure of information among people or software agents,
- (ii) enable reuse of domain knowledge,
- (iii) make domain assumptions explicit,
- (iv) separate domain knowledge from the operational knowledge, and
- (v) analyze domain knowledge.

The Web Ontology Language (OWL) [6], which has been optimized to represent structural knowledge at a high level of abstraction, can be used to formalize web content and create domain-specific models that can be shared and reused across the web. Applications that will share these models will gain the advantage of interoperability.

The idea of modelling the components of embedded systems using ontologies is not new. Research groups have constructed such ontologies for various domains, for example, the device ontology for the mobile communications domain [36]. Most of these works are based on the Fipa-device specification [37] and propose extensions to cover the spe-

cific domain. Others have identified the significance of the device modelling in the context of domain-specific frameworks, for example, in [38] for the definition of a visualization approach for collaborative planning systems, and in [39] for knowledge systematization in the construction process of knowledge models for manufacturing.

3. THE PROPOSED SERVICE-ORIENTED FRAMEWORK FOR EMBEDDED SYSTEMS

The proposed SOA-based framework was evolved as an extension of Corfu [40] and Archimedes system platform [41]. The main objective is to address the restrictions imposed by traditional embedded systems development environments and to further extend the provided functionality regarding system layer modelling, as well as deployment and redeployment of the application layer components to the runtime infrastructure.

The service is the basic construct of the proposed architectural framework as shown in Figure 1. Functions are defined as independent services with well-defined invokable interfaces which can be called in defined sequences to form the processes required for the development, deployment, and execution of industrial automation software. Services of

the framework implement model definition and model editing functions, implementation model generation functions, component-type repository functions for the discovery of required component types, deployment functions, as well as monitoring functions.

Services, which should be completely independent of one another, should operate as black-boxes, without the need for clients to neither know nor care how these services perform their function. A service is described by means of WSDL providing invokable interfaces, which define not the technology used to implement it but the nature of the service through the required parameters and the nature of the result. At the architectural level, it is irrelevant whether these services are within the same or different address space or even provided by the same or various vendors. It is also irrelevant what interconnection scheme or protocol is used for the invocation, or what infrastructure components are required to make the connection.

It is expected that a great number of services will appear to provide generic functionality as well as specific functionality required in specialized application domains. In any case, the definition of services in such an environment is a challenge since it should be based on many parameters such as performance, flexibility, maintainability, and reuse. An interesting question not answered yet has to do with the level of granularity that functions will be mapped to services.

It should be noted that web services in most of the cases do not meet the resource constraints imposed by embedded devices and also introduce a great overhead that results in an order-of-magnitude performance difference comparing with other service-based technologies such as real-time CORBA. This is the reason for using web services in the context of this approach only for the development process.

The proposed framework intends to enable industrial engineers to set up and customize the Engineering Support System (ESS) that best fits with the needs of their project. The big advantage of this approach is that these services are sold and assembled on demand. The industrial engineer, instead of buying or developing software components and binding them together to form a custom ESS, will construct the project-specific ESS as an orchestration of web services. Selected web services are only used and bound together at the time of use of the particular feature of the ESS, as shown in Figure 2, where the conceptual model of the proposed framework is presented. The term ESS is introduced by the IEC61499 standard to refer to an enhanced IDE used not only in the design and implementation, but also in the commissioning as well as the operation phase of industrial automation systems.

Industrial engineers using the proposed framework can either assemble their services out of existing ones from the service layer infrastructure, or define and develop atomic services to implement their own desirable features using traditional development techniques. These services can be later incorporated in the service layer infrastructure.

This provides a powerful and flexible framework for customizing and yet extending the environment to address the industrial engineer's particular requirements. It enables the industrial engineer to construct an ESS by using services by

multiple suppliers to meet the needs of the specific project. It should be noted that the so-defined development environment must include and enforce a methodology that will clearly prescribe how services and components will be designed and built in order to facilitate reuse, eliminate redundancy, and simplify testing, deployment, and maintenance. Such a methodology is also required to guide the industrial engineer through the development process.

The project-specific ESS will be used by embedded systems' developers to construct or find the required hardware or software constituent components and use their models in the development and operational phases of their systems. One such component is the physical device that provides storage, processing, and communication capabilities required for the execution of the software components. The remainder of this section focuses on the modelling of the device to show the way that the proposed framework enhances the effectiveness of the development process of industrial automation embedded systems.

Specific web services are defined to semi-automate the development process regarding device handling and more specifically (a) the construction of generic-embedded boards, (b) the construction of domain-specific devices, (c) the design process of the system layer as an aggregation of interconnected devices, (d) the deployment process, and (e) the verification process. For these web services to interoperate through orchestration in order to constitute a coherent ESS, the sharing of common models for the device is a prerequisite. Technologies of the semantic web are exploited to formalize device descriptions and make them machine-interpretable so that they can be more easily used by web services to assist the system engineer in device handling. The next section describes our ontology-based modelling of the device that satisfies the requirements of this approach.

3.1. Services for device vendors

A specific web service should provide the functionality required by vendors of embedded boards, shown in (1) of Figure 2, to create the models of their generic devices in the form of OWL documents. This functionality is currently provided by Protégé [42] and other ontology tools, but an enduser-oriented service such as the one we have developed in our prototype environment is required. This service parses the ontology and creates a GUI to allow the user to capture the attributes of the specific device, that is, the embedded board's data sheet. The result is an enhanced data sheet in the form of an OWL document that will be published on the web ((2) in Figure 2).

Vendors that develop domain-specific devices will discover, through a semantically annotated UDDI, semantically annotated WSs that provide the functionality of dynamically creating GUIs to capture the search criteria for the required embedded board (3). Such an sWS will exploit the embedded board ontology selected by the user, to dynamically create a GUI to allow the user to define the search criteria, that is, the specific requirements that the requested device should meet. The created GUI will be in the form of an HTML document or in the form of an OWL document if ontologies are

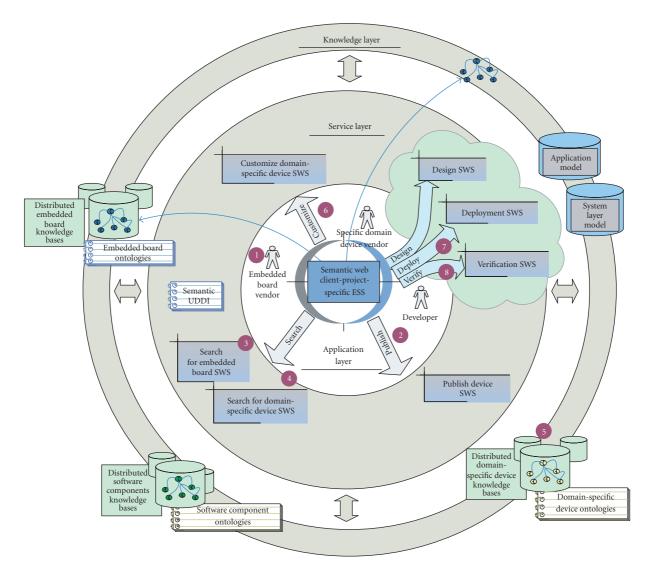


FIGURE 2: Conceptual model of the proposed semantic web-based framework.

used to describe GUIs [43]. It should be noted that different implementation scenarios exist regarding the distribution of functionality in client-server sides to better exploit the advantages of semantic web. It is a matter of choice and architecture as to which functionalities will run locally and this decision mainly depends on the tools that will evolve to exploit the semantic web. It is expected that functionalities described above will soon be part of the next generation semantic web browsers relieving the developer from the task of creating sWSs to implement these functionalities.

The user's search criteria will be formalized using the semantic web rule language (SWRL) [44] that can describe any kind of restrictions upon ontology concepts. Alternatively, a query expressed in SPARQL [45] or any other query language can be generated to directly access a knowledge base with embedded board descriptions. In any case, this sWS interface must be described in OWL-S [46] that provides a standard vocabulary that can be used to create service descriptions and enable users and software agents to automatically

discover, invoke, compose, and monitor web resources. This OWL-S defined sWS interface specifies the service grounding for a dynamically constructed stub client required to invoke the corresponding service method which is able to locate the embedded boards that meet the defined search criteria. A set of device models that meet the search criteria is the result of this sWS.

Device vendors of a specific domain, following an analogous process with the one applied by vendors of embedded boards, will create the owl documents that describe their devices and publish them on the web. Some unclear issues exist in this process, for example, the way of using the embedded board model in the process of constructing the specific device model that has to be supported by the ontology-instance generation web service.

3.2. Services for the industrial engineer

During the design phase of the system layer, that is, the hard-ware/software infrastructure required to execute the software

application, the industrial engineer searches (4) through the ESS the web to locate devices that meet required QoSs. These QoSs are imposed either by the controlled process, for example, number and type of process parameters to be sensed or actuated, or by the components of the software application, for example, number and functionality of Function Block types used in an IEC61499-based application. Through semantically annotated web services, the industrial engineer performs an ontological search based on concepts that are described in the domain-specific device ontology (5). Access to basic characteristics of the device is guaranteed since this information is also included in the device model that was constructed by the vendor.

Devices are usually described in terms of optional configurations. A device, for example, may be configured to have various types of I/Os or support various operating systems. A specific web service, that will have the ability of manipulating ontologies relieving the industrial engineer from this task, will allow the description of the desired configuration (6) imposed by the specific application. Choices will be made in a user friendly way and the web service will create the device model of the defined configuration. This device model can be downloaded and used for the design of the system layer.

The use of the device model is also important during the deployment process (7). That is when decisions must be made about the distribution of the application's components and the generation of the application implementation model. During this process, the device model can be automatically updated with the use of rules and rule engines every time its available resources change, for example, when components are downloaded and instances are created. Based on this, the industrial engineer will always be aware of the remaining resources. Specific functionality provided by the ESS may be utilized to search for possible alternatives that satisfy the QoSs which are required by the application layer components.

Finally, the device model may be utilized through the verification process (8) of the design model. Device descriptions in the form of knowledge bases for the specific project will be stored in the project's repository and will be exploited by design-model analysis and verification tools to verify that the application's design diagrams, as well as the planned deployment scenarios, are implementable. Later on, and after the verification of the design models of the DES, the real devices can be bought using the appropriate web service and used for the implementation of the industrial system.

4. DEVICE MODELLING

The embedded application may run on one device but its components are usually downloaded and executed on a network of interconnected devices. The system layer diagram is considered as an aggregation of interconnected devices where interconnecting edges provide the infrastructure required for the realization of component interactions that cross device boundaries.

A large number of heterogeneous devices of different vendors are used for embedded systems development. Since, these devices can only be handled by proprietary tools that are provided by their vendors, different tools must be used today in the life cycle phases of embedded systems in industrial automation. The need for information exchange between these tools makes the task of integration very difficult. Moreover, the large number of different device types and suppliers within a given embedded system makes the configuration task difficult and time consuming.

It is also clear that the different proprietary device tools coming from a variety of device vendors cannot be consistently integrated into a coherent toolset. The problem of configuring and parameterizing heterogeneous devices during the operation diagnosis, parameter tuning, processing purposes, etc. constitutes one of the most important challenges in the development process.

4.1. The need for device modelling

Descriptions of devices already exist on the web either in the form of data sheets or in the form of electronic device description that is a common way of describing programmable logic controllers (PLCs), that is, electronic devices widely used for automation of industrial processes. However, since data sheets are constructed in the traditional way, that is, using presentation languages such as HTML, embedded system developers should use their web browsers to search for the specific devices that meet their requirements. These descriptions are very difficult if not impossible to be utilized by IDEs to semi-automate the development process.

This problem was recognized very well in the industrial automation domain where different device models [47–50] were constructed to address this demand. Device Description Languages (DDLs) already support the specification of field devices, with HART DDL [47], Profibus Device Description [48], and Foundation Fieldbus DDL [49] being among the most important. These notations are used to represent the properties of a field device in a proprietary machine-readable format to be used by proprietary engineering tools during the development phase. The specification is also used during the system's operation phase.

However, there is no common model for the device specification, and the above notations result in incompatible device specifications. A device model consistent with current software engineering practices should be defined to enable the new generation IDEs to further automate the development and deployment process. Operations to be supported by such a device model include the following.

- (i) Select the device that meets the QoS characteristics required by the software application components.
- (ii) Configure the device to meet the requirements of the current system.
- (iii) Semi-automate the deployment and redeployment processes.
- (iv) Create the dynamic model of the device that represents the device at run time.

The Field Device Markup Language (FDCML) is an attempt to address the above requirements in the industrial automation domain. It is an XML-based device

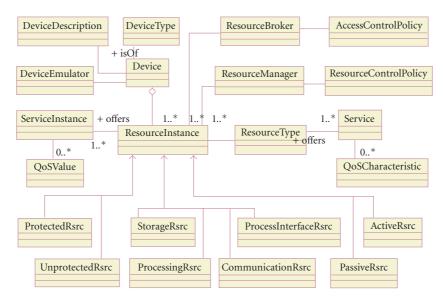


FIGURE 3: Part of the constructed device model expressed in UML notation [51].

specification standard [52] for field components to allow a tool-independent device description whose format can be used by many applications. FDCML defines the device profile as an aggregation of four basic elements: device-identity, device-manager, device-function, and application-process. It has also extensibility elements to provide the appropriate flexibility for extending the model. However, except from the fact that the XML schema that is based on is not available, FDCML does not fully cover the device-application and device-function elements, which are of great importance to our approach.

4.2. A UML device model

A prototype model was defined for the device to address the requirements imposed by the development process. As shown in Figure 3, where part of this model is shown, the resource is the key concept in this model. A device is of a specific DeviceType and is considered as an aggregation of ResourceInstances, where each ResourceInstance is of a specific ResourceType. The UML profile for Schedulability, Performance, and Time Specification [53] was utilized for the modelling of resource so as to represent all the quantitative aspects of both software and hardware. A resource is considered as a server that provides one or more services to its clients [54], with the physical limitations of services to be represented through QoS attributes. The QoS concept is used in the context of this framework to establish a uniform basis for attaching quantifiable information to UML models. QoS information represents directly or indirectly the physical properties not only of the application's components in the form of required QoS, but also those of the hardware and software infrastructure used to execute the control application (offered QoS).

UML's extensibility mechanisms can be used to create a more expressive model for the device. The construct of stereotype is used to define a specialization of the class construct to add the semantics of the device to the class UML construct. Additional constraints and tagged values are used to represent additional attributes of the device. The tagged value "IEC61499-compliance" is used to define a QoS characteristic of this device that is the class that the specific device supports regarding its compatibility with the IEC61499 standard. The device model that was created can be used by device vendors to construct the models of their devices.

We discriminate two approaches for the definition of the device model from vendors and the whole device modelling policy:

- (i) modelling by instantiation, and
- (ii) modelling by extension.

The first one exploits the concept of metamodelling. The device model for the specific domain, that is, an IEC-61499-compliant device, is considered as an instance of a generic model that is the metamodel. The metamodel captures all these constructs that are required to create device models for different categories of devices. Assuming such a metamodel, domain experts can define the IEC61499-compliant device model as an instance of the generic metamodel.

The second approach is based on a generic device model that captures the generic attributes and the common behavior of all devices. This model can be specialized by extension to include the specific attributes and behavior of the modelled kind of devices. The result of this process for the IEC 61499 domain will be an IEC61499-compliant device model.

In both cases, the device vendors should exploit the IECcompliant device model to construct the models of their devices as instances of it.

4.3. Using ontologies for device modelling

The device model that was created in this way is impossible to be used by different tools to share this knowledge and cooperate to constitute a coherent toolset for DESs. Technologies

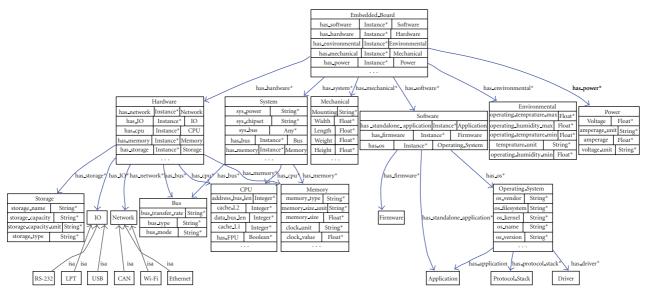


Figure 4: The generic embedded board ontology (part).

of the semantic web, such as the OWL, can be exploited to formalize device descriptions and make them machine-readable so that they can be more easily analyzed by IDEs to assist the developer in the decision making processes involved in system development.

Device vendors instead of developing their own device model will be able to locate a suitable device model on the web and simply reuse or extend it. By reusing these models, different web services can share results and data much more easily and simplify their integration to form a consistent ESS. The semantic web is used as a platform on which the domain-specific device model will be created in such a way that sharing and reusing by many different applications across the web will be the primary objective. This means that the proposed framework should provide the infrastructure required for networking, as well as for merging and alignment of ontologies [34], which will be used as enabling technologies to this direction.

Using this approach, domain-specific models for devices, but also for other software and hardware artefacts, can be constructed, uploaded, and linked into the web, so that custom eSESEs can link and utilize them. The device ontology, for example, will be defined to represent the common conceptualization that is required to increase the degree of automation in the system layer development process. This device ontology should define the meaning of the concepts of a common device model in a machine-processable format and should facilitate the processing of information of heterogeneous devices in the design phase of the system layer diagram. It will also describe the device characteristics concerning storage, processing, and communication capabilities of the device.

4.4. Modelling the device with a networked ontology

To proceed with the device modelling, we define an embedded board ontology that captures the key concepts in-

volved in data sheets of the embedded boards available in the market, for example, EmCORE-v621, RSC-7820, and PEB-2530VL. These boards are used by vendors as basis for the construction of more enhanced devices with specific characteristics for a given embedded application domain. The FIPA-device ontology [37], which is an early attempt towards a device model, captures only the basic device concepts providing a very generic model that can be used as basis for more detailed device ontologies. Figure 4 presents part of the defined embedded board ontology as visualized in Protégé. In this figure, only the fundamental classes of the proposed ontology are depicted along with some of their essential properties. Although it is not illustrated in the given diagram, the embedded board ontology can easily exploit the FIPAdevice ontology, since hardware and software classes can be defined as subclasses of hardware-description and softwaredescription classes of the FIPA ontology, respectively.

Since it is expected that many different ontologies will appear to model the embedded board in different ways, ontology alignment [55] would allow preservation of the original ontologies by establishing different kinds of mappings or links between these different ontologies. Means should be provided by the adopted ontology implementation language to dynamically interconnect distributed ontologies and support reuse of already defined concepts. OWL that was adopted in the context of the proposed framework provides specific primitives to this direction.

Vendors use generic-embedded boards as basis to construct devices for the specific domain. To create the device models for the specific domain, a new ontology that should specialize the embedded board ontology is required. For example, the IEC61499-compliant device ontology will be created to describe the IEC61499-compliant devices that would be developed by vendors for the control and automation domain. Figure 5 shows a part of this ontology that captures some of the key concepts of an IEC61499 device, such as

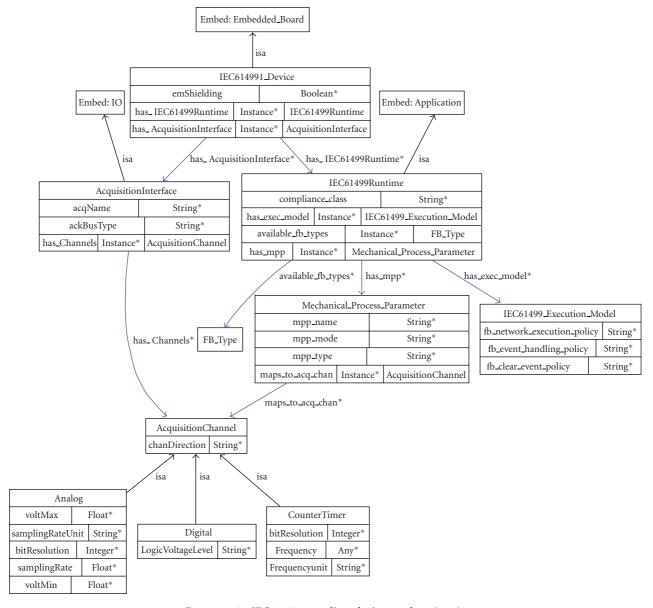


FIGURE 5: An IEC61499-compliant device ontology (part).

the IEC61499 run-time environment, the adopted execution model description, and the available I/Os depicted as acquisition channels along with the mapping to their software counterpart. The relationship to generic-embedded board concepts is also depicted using a subclass relation.

5. A PROTOTYPE IMPLEMENTATION

A prototype implementation was developed to demonstrate the applicability of the proposed approach in the industrial automation domain. Web services for searching, locating, and obtaining software components from vendors' component repositories, services for component implementation model generation, and services for device handling were defined and developed. Specific clients that exploit these WSs have also been developed to provide the industrial engineer with a user friendly access to the knowledge and service layer infrastructure. For example, the ontology population client that is shown in Figure 6 supports a user friendly construction of the embedded board model as an ontology instance and its subsequent publication to a knowledge base. The embedded board vendor has to select the desired embedded board ontology to be used for the modelling of his embedded board. The client parses the selected ontology and creates a form that can be used to capture the embedded board characteristics that are represented as individuals. This information is used to create an OWL document that is the machine-understandable data sheet of the embedded board and can be stored either locally or published to an existing knowledge base. The client can either use a local embedded repository, for example, the Minerva OWL ontology repository [56] to store the constructed device model, or access

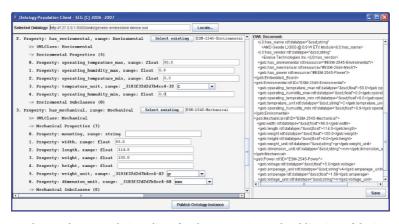


FIGURE 6: The ontology population client for the generation and publication of device models.

an appropriate web service to publish it on a remote ontology repository. The specific client has been developed using the IBM Integrated Ontology Development Toolkit (IODT) [56].

The web services and the corresponding prototype clients were implemented as Java 1.5.0 servlets. Eclipse 3.1.2 with the Web Standard Tools (WST) plugin was used to construct a web service following a bottomup approach and selecting the methods from our implementation that should be publicly exposed. The constructed web service servlets were deployed on appropriate servlet container and their WSDL descriptions were published on our UDDI. These WSDL descriptions were later utilized for the automatic generation of stub clients through the WST Eclipse plugin. Version 1.0.2 of the plugin was utilized for the development of the services, while version 1.0.1 was used for the development of prototype clients.

The web services are currently deployed on Tomcat 5.5.17 servlet container, while the API used to handle the SOAP messages is Apache Axis. The Apache jUDDI, which gives an interaction interface through filling XML documents with the appropriate information, was utilized to implement our UDDI service. The provided UDDI with prototype implementations can be reached at http://seg.ece.upatras.gr/seg/dev/SOA4DCS.htmseg/dev/SOA4DCS.htm.

5.1. Software component-related web services

Services of this category include FB-type repository web services, which are key services for increasing reusability, and implementation-model generation web services, which transform FB-type design specifications to executable specifications

Services of the first category allow the control engineer to locate already available Function Block- (FB-) type specifications and use them in the development process. It also allows vendors to develop generic and specific FB types and advertise them for sale through the web infrastructure. If such an infrastructure will be established, it is estimated that a lot of machine and tool vendors will provide specific web services that will allow industrial engineers to search and locate the

FB types that better match the requirements of their application. All the above simplify the use the FB-type repository from both the costumer and the provider point of view.

A prototype web service to demonstrate this concept was developed and published in our UDDI service. This service can be accessed by industrial engineers either using the WSDL interface or using a prototype web service client such as the one we have developed. Such a client invokes the service and presents the requested information assuming that it is provided with the appropriate parameters. A snapshot of this client interface representing the ids and names of all FB types contained in the ARM_Project_new FB-type package is presented in Figure 7.

It is clear that this implementation allows searching and retrieving of FB-type specifications using their name, id, relevant package categorization, and text describing information. A more effective implementation can be obtained if the whole process is based on an FB-type ontology. With such an ontology, FB-type repositories turn to knowledge bases of FB-type descriptions, thus allowing the flexible discovery of FB types based on search criteria that refer to the various ontology concepts.

Services of the second category, that is, the implementation-model generation WSs, are used to transform the FB-type design specifications to executable specifications, that is, the implementation models, for a specific platform. Model-to-model transformers, as the one used to create the implementation model of the FB type in a specific implementation environment, that is, Java, C++, CCM, and so forth, will also be provided by vendors as web services. A prototype web service of this category was developed and published in our UDDI service. An independent generator written in Java using the Xerces Parser was utilized to construct a servlet-based web service that accepts an FB-type specification as attachment in XML form and returns the corresponding C++ generated library source code.

The FB-type implementation model generation WS may utilize technologies of semantic web to allow a flexible, parametrical, and implementation model generation process for various run-time environments. This assumes an appropriate run-time environment ontology that should capture the

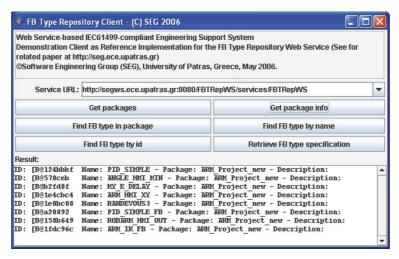


FIGURE 7: A simple web service client using the FB-type repository web service.

execution characteristics of the target environment that the generator can utilize. An extension we are currently working on assumes the existence of an IEC61499-compliant ontology for the specification of FB types. According to this approach that greatly simplifies the handling of components through the development process, FB types will appear in vendors' FB-type knowledge bases as instances of this ontology.

Web services of this last category can be utilized automatically by the ESS during the deployment phase to get the target device implementation model of the FB types assigned to the specific device.

5.2. Device-related web services

A set of web services has been defined for the device handling to demonstrate the enhancement of the development process through the use of ontologies. Web services of this category include device model generation, device discovery, device model extension, and device model customization web service.

Our prototype device-discovery web service receives queries in SPARQL, accesses the knowledge base with the embedded board specifications based on the embedded board ontology as shown in Figure 8, and returns the owldocument specifications that meet the user's search criteria. This web service has been published in a private UDDI to allow for any user to locate and use it through a WSDL interface which is also published on the same UDDI. The Minerva engine, a high-performance OWL ontology storage, inference, and query system, is utilized for the implementation of the device ontology repository. Protégé that was initially used for the initial development and population of ontologies could also be used for the same purpose.

The device-discovery client that was developed can parse well-formed ontologies and create a GUI such as the one shown in Figure 9, upon which the user can define the search criteria based on parameters of ontology concepts. Based on the search criteria, the client formulates constraints in SPARQL queries and forwards them to the device-discovery web service. Alternatively, the client may directly access the Minerva-based knowledge base and issue a SPARQL query, but in a uniform SOA-based environment, a mediation of a WS is the best choise. Moreover, the mediating WS may also act as broker that transparently queries multiple knowledge bases. It should be noted that this part of client's functionality that parses the ontology and creates the GUI can also be assigned to the web service. In this case, only a stub client that is dynamically generated by the WSDL is required. Moreover, such an approach, that is, giving the end user client the ability to parse and handle knowledge described in ontologies and directly use the semantic web, relieves the user from the extra effort of using remote services. This feature along with others such as using SWS described in OWL-S or other semantic languages, direct access to KBs using query languages as SPARQL, and GUI generation techniques to aid human machine interaction will be part of the functionality of the next generation browsers.

6. CONCLUSIONS

Currently available or under development component models and corresponding ESSs do not provide the flexibility required from the development process of complex tomorrow's agile industrial systems. The most important limitations to this inability are introduced by the traditional architectural paradigms that are utilized to construct them.

The service-oriented architectural paradigm was adopted to define a framework for the easy integration of desirable features and their customization to form project-specific ESSs. Specific web services were developed to demonstrate the applicability of this approach. For the better integration of the different web services, the need for a common domain-specific device model was identified. UML was used to define a generic model for the device. However, to get the best in terms of interoperability and reusability from the so-defined models, semantic web technology should be exploited. A prototype device ontology was developed using

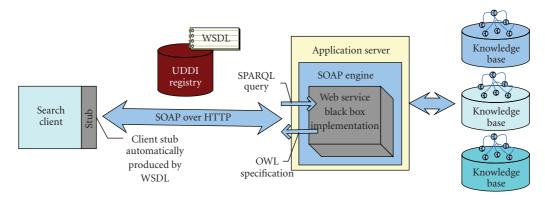


FIGURE 8: The embedded board search service and client.

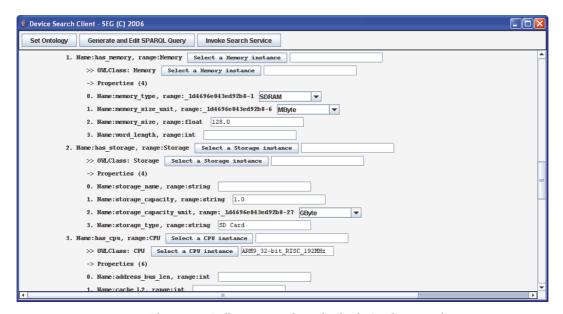


FIGURE 9: The automatically constructed GUI by the device-discovery client.

Protégé and its use in the different phases of the development process was examined. The resulting framework benefits both from the adopted service-oriented architectural paradigm and the semantic web technology to provide a promising platform for the next-generation ESSs for the industrial systems domain.

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